

# Math 3280 Practice Midterm 2 Solutions

- (1) Find the general solution to the ODE:  $y^{(3)} - 5y'' + 12y' - 8y = 0$ .

Solution: The characteristic equation is  $r^3 - 5r^2 + 12r - 8 = 0$ . If we believe in a benevolent testwriter, it is natural to look for integer solutions to polynomials of degree larger than two. So we could try  $1, -1, 2, -2, 4, -4, 8, -8$ . Happily it is easy to check that 1 is a root, so the characteristic polynomial has  $(r - 1)$  as a factor. After dividing out this factor (you should know how to do polynomial division!) we get  $r^2 - 4r + 8$ . From the quadratic equation we can then find the full factorization  $(r - 1)(r - (2 - 2i))(r - (2 + 2i))$ . The general solution is  $y = C_1 e^x + e^{2x}(C_2 \sin(2x) + C_3 \cos(2x))$

- (2) Find the solution to the initial value problem  $y'' - 2y' + 5y = e^{2x}$ ,  $y'(0) = 0$ ,  $y(0) = -1$ .

Solution: We begin by finding the general solution  $y = y_h + y_p$ . The homogeneous solution  $y_h$  is determined by the characteristic equation  $r^2 - 2r + 5 = (r - (1 + 2i))(r - (1 - 2i))$ :  $y_h = e^x(C_1 \cos(2x) + C_2 \sin(2x))$ .

We can find the particular solution  $y_p$  by the method of undetermined coefficients, i.e. we suppose that  $y_p = Ae^{2x}$  and solve for  $A$ . Plugging in this form and dividing out the  $e^{2x}$  factors we find that  $4A - 4A + 5A = 1$ , or  $A = 1/5$ .

Now the initial conditions can be used to determine  $C_1$  and  $C_2$ . The condition  $y(0) = -1$  becomes  $C_1 + \frac{1}{5} = -1$  and  $y'(0) = 0$  becomes

$$2e^x C_2 \cos(2x) + e^x C_1 \cos(2x) + e^x C_2 \sin(2x) - 2e^x C_1 \sin(2x) + \frac{2e^{2x}}{5} \Big|_{x=0}$$

$$= \frac{2}{5} + C_1 + 2C_2 = 0.$$

The first equation can be immediately solved for  $C_1 = -\frac{6}{5}$  and then the second for  $C_2 = \frac{2}{5}$ . So the solution is  $y = e^x(-\frac{6}{5} \cos(2x) + \frac{2}{5} \sin(2x)) + \frac{1}{5}e^{2x}$ .

- (3) Write down the form of a particular solution  $y_p$  of the ODE  $y'' + y = x^2 e^x + \cos(x)$ . You do not have to determine the coefficients of the functions.

Solution: The problem is a little harder than it might look because one of the functions on the righthand side also appears in the homogeneous solution  $y_h = C_1 \cos x + C_2 \sin x$ . So we have to add a power of  $x$  in the undetermined particular solution:  $y_p = Ax \cos x + Bx \sin x + Ce^x + Dxe^x + Ex^2 e^x$ .

- (4) If an  $n \times n$  matrix  $A$  has the property that  $A^3 = 2A$ , what are the possible values of the determinant of  $A$ ?

Solution: Taking the determinant of both sides of the equation gives us  $\det(A^3) = \det(2A)$ . Because of the multiplicative property of determinants,  $\det(A^3) = (\det(A))^3$ .

Since each row of  $2A$  has been multiplied by 2,  $\det(2A) = 2^n \det(A)$ . Then we have

$$(\det(A))^3 - 2^n \det(A) = \det(A)((\det(A))^2 - 2^n) = 0$$

so either  $\det(A) = 0$  or  $\det(A) = \pm 2^{n/2}$ .

- (5) Solve the initial value problem  $y''' - 27y = e^{3x}$ ,  $y(0) = y'(0) = y''(0) = 0$ .

Solution:

First we find the homogeneous (also called complementary) solution to

$$y_c''' - 27y_c = 0.$$

To do this we have to factor the characteristic equation  $r^3 - 27 = 0$ .

One root is easy to get:  $r_1 = (27)^{1/3} = 3$ .

If we divide  $r^3 - 27$  by  $r - 3$ , the quotient is  $r^2 + 3r + 9$ .

With the quadratic formula we can get the other two roots,  $r_2, r_3 = -\frac{3}{2} \pm \frac{3\sqrt{3}i}{2}$ .

With these three roots, we can construct the complementary solution:

$$y_c = C_1 e^{3x} + C_2 e^{-\frac{3t}{2}} \cos\left(\frac{3\sqrt{3}t}{2}\right) + C_3 e^{-\frac{3t}{2}} \sin\left(\frac{3\sqrt{3}t}{2}\right)$$

Next, to find the particular solution we would normally use the method of undetermined coefficients with the form  $y_p = Ae^{3x}$ .

But this is contained within the complementary solution, so instead we use

$$y_p = Axe^{3x}.$$

Since  $y_p''' = 27xAe^{3x} + 27Ae^{3x}$ , we require that

$$\begin{aligned} y_p''' - 27y_p &= 27xAe^{3x} + 27Ae^{3x} - 27xAe^{3x} \\ &= 27Ae^{3x} = e^{3x} \end{aligned}$$

and so  $A = 1/27$ .

So the general solution to the ODE is

$$y = y_c + y_p = C_1 e^{3x} + C_2 e^{-\frac{3t}{2}} \cos\left(\frac{3\sqrt{3}t}{2}\right) + C_3 e^{-\frac{3t}{2}} \sin\left(\frac{3\sqrt{3}t}{2}\right) + \frac{1}{27} x e^{3x}$$

The initial condition  $y(0) = 0$  becomes  $C_1 + C_2 = 0$ . Since

$$y' = -\frac{3}{2}(\sqrt{3}C_2 + C_3)e^{-\frac{3x}{2}} \sin\left(\frac{3\sqrt{3}}{2}x\right) + \frac{3}{2}(\sqrt{3}C_3 - C_2)e^{-\frac{3x}{2}} \cos\left(\frac{3\sqrt{3}}{2}x\right) + (3C_1 + \frac{1}{27} + \frac{x}{9})e^{3x}$$

$$y'(0) = \frac{3}{2}\sqrt{3}C_3 - \frac{3}{2}C_2 + 3C_1 + \frac{1}{27} = 0$$

Now we compute the equation for the initial condition  $y''(0) = 0$

$$y'' = \frac{9}{2}e^{-\frac{3x}{2}} \left( (\sqrt{3}C_2 - C_3) \sin\left(\frac{3\sqrt{3}}{2}x\right) + (\sqrt{3}C_3 + C_2) \cos\left(\frac{3\sqrt{3}}{2}x\right) \right) + e^{3x} \left( 9C_1 + \frac{2}{9} + \frac{x}{3} \right)$$

$$y''(0) = -\frac{9}{2}\sqrt{3}C_3 - \frac{9}{2}C_2 + 9C_1 + \frac{2}{9} = 0$$

Writing all of these initial conditions as a matrix-vector system we get:

$$\begin{pmatrix} 1 & 1 & 0 \\ 3 & -\frac{3}{2} & \frac{3}{2}\sqrt{3} \\ 9 & -\frac{9}{2} & -\frac{9}{2}\sqrt{3} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \end{pmatrix} = \begin{pmatrix} 0 \\ -1/27 \\ -2/9 \end{pmatrix}$$

The row-reduced echelon form of the augmented coefficient matrix is

$$\begin{pmatrix} 1 & 0 & 0 & -\frac{1}{81} \\ 0 & 1 & 0 & \frac{1}{81} \\ 0 & 0 & 1 & \frac{1}{243}\sqrt{3} \end{pmatrix}$$

So finally we have:

$$y = \frac{1}{81} \left[ e^{-\frac{3x}{2}} \left( \frac{\sqrt{3}}{3} \sin\left(\frac{3\sqrt{3}}{2}x\right) + \cos\left(\frac{3\sqrt{3}}{2}x\right) \right) + (3x - 1)e^{3x} \right]$$

- (6) Find a basis for the subspace  $S$  of solutions to the system within the vector space  $\{(x_1, x_2, x_3, x_4, x_5, x_6) \mid x_i \in \mathbb{R}\} = \mathbb{R}^6$ :

$$\begin{aligned} x_1 - x_2 + x_4 + 4x_5 &= 0 \\ x_1 + x_2 + x_4 + 4x_5 + x_6 &= 0 \end{aligned}$$

Solution:

We row reduce the coefficient matrix:

$$\begin{pmatrix} 1 & -1 & 0 & 1 & 4 & 0 \\ 1 & 1 & 0 & 1 & 4 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 & 4 & 1/2 \\ 0 & 1 & 0 & 0 & 0 & 1/2 \end{pmatrix}$$

This shows that  $x_1$  and  $x_2$  are pivot variables, while the others are free. We write the solution in terms of the free variables:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} = \begin{pmatrix} -x_4 - 4x_5 - x_6/2 \\ -x_6/2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} =$$

$$x_3 \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} -4 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} + x_6 \begin{pmatrix} -1/2 \\ -1/2 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

So a basis for  $S$  is the set

$$\left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1/2 \\ -1/2 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

- (7) Rewrite the initial value problem  $y''' + y'' + y = t$ ,  $y(0) = y'(0) = y''(0) = 0$  as an equivalent first-order system.

Solution: Introduce the variables  $v_1 = y'$ ,  $v_2 = v'_1 = y''$  and the system becomes:

$$y' = v_1$$

$$v'_1 = v_2$$

$$v'_2 = t - v_2 - y$$

$$y(0) = 0, v_1(0) = 0, v_2(0) = 0$$

Note that rewriting the initial conditions is a required part of this answer.

- (8) The matrix

$$A = \begin{pmatrix} a & b & 0 \\ -b & a & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

where  $a$  and  $b$  are real numbers, is diagonalizable, i.e. there exists a matrix  $P$  such that  $P^{-1}AP = D$  where  $D$  is diagonal. Compute  $D$ .

Solution:

$$D = \begin{pmatrix} a + bi & 0 & 0 \\ 0 & a - bi & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

(any other order of the eigenvalues on the diagonal is also correct).

- (9) Indicate whether each of the following statements is true or false.

- (a) The set of solutions  $(x, y, z) \in \mathbb{R}^3$  to the equation  $x + y + z = 0$  is a vector subspace of  $\mathbb{R}^3$  of dimension 2.

Solution: True. A single linear homogeneous constraint will have a solution set that is one dimension less than the ambient vector space. Alternatively we can compute this by row-reducing the coefficient matrix of the system, which in this case is the matrix  $[1, 1, 1]$ . This is already in row-reduced echelon form, with one pivot and two free variables ( $y$  and  $z$ ). The number of free variables is the dimension of the solution set.

- (b) The set of solutions  $(x, y, z) \in \mathbb{R}^3$  to the equation  $x + y = 1$  is a vector subspace of  $\mathbb{R}^3$  of dimension 2.

Solution: False. This is a nonhomogeneous system, so the solutions do not form a vector subspace.

- (c) The set of solutions to the differential equation  $y'' + xy' + x^2y = 0$  is a vector space of dimension 2.

Solution: True. See Theorem 4 of section 5.2.

- (d) The set of solutions  $(x, y, z) \in \mathbb{R}^3$  of the system below is a vector subspace of  $\mathbb{R}^3$  of dimension 1.

$$\begin{aligned} x + 2y + 3z &= 0 \\ 4x + 5y + 6z &= 0 \\ 7x + 8y + 9z &= 0 \end{aligned}$$

Solution: True. The coefficient matrix has a row-reduced form with two pivots and one free variable.

- (e) The polynomials  $1+x$ ,  $1-x$ ,  $1+x^2$  are a basis for the vector space of polynomials with real coefficients of degree less than or equal to 2.

Solution: True. A more obvious basis would be  $1, x, x^2$ , which can be obtained from these polynomials as linear combinations:  $1 = (1+x)/2 + (1-x)/2$ ,  $x = (1+x)/2 - (1-x)/2$ , and  $x^2 = -(1+x)/2 - (1-x)/2 + (1+x^2)$ .